# The Classification Tree Combined with SIR and Its Applications to Classification of Mass Spectra

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A new approach combining classification tree (CT) with Abstract: sliced inverse regression (SIR) is proposed and applied to the classification of mass spectra in this paper. The classification tree has been widely used to generate classifiers from the mass spectral data because of its powerful ability in automatic variable selection and automatic interaction detection. However, it is often weak on presenting the linear and global relationships among variables. When the variables enter a model with the form of linear combination, the classification tree can not detect the form and leads to a low accuracy. SIR is an effective method to find useful linear combinations of predictor variables to regress the response variable. So merging CT and SIR harmoniously can inherit both advantages of them. Experiments in the paper show that the proposed approach can improve classification accuracy of decision tree and get better result than other classical classification methods.

*Key words:* Classification of mass spectra, classification tree, data mining, sliced inverse regression.

## 1. Introduction

Mass spectrometry, an instrumental technique which is used to character and identify chemical compounds, produces large amounts of valuable data for the chemical structure elucidation. In a mass spectrometer, molecules

of the investigated substance are ionized and the produced ions are separated according to their mass-to-charge ratio (m/z, mostly z=1) and the abundances of these separated ions are measured. Then a mass spectrum, bar plot with m/z versus abundance of ions (peak height) is provided. At present, the NIST 98 MS Database contains about 100,000 mass spectra with their corresponding chemical structures and the Wiley/NBS collection includes even more mass spectra to about 130,000 (NIST 98 MS Database and Wiley/NBS collection). How to extract the chemical structure information contained in these mass spectra? How to identify compounds and recognize structural properties automatically from mass spectral data? These are still open problems in chemometrics and have been attracted by many authors.

One group of strategy which has been widely applied to above problems is the classification methods based on multivariate statistics and data mining. Consider peak heights at integer mass-to-charge ratio as input variables and chemical structure properties, for example, the presence or absence of a certain chemical substructure, as response variables, classification methods can be used to find relationship between the structure properties and mass spectra or to train classifiers for automatic recognition of structural properties. There have been many kinds of classification techniques applied in this field, such as K-nearest neighbor classification, linear discriminant analysis, principal component analysis, neural networks, and classification tree. Knearest neighbor (KNN) is a local averaging method. Linear discriminant analysis (LDA) and principal component analysis (PCA) are both globally linear method. Neural network (NN) is the learning method based on the artificial intelligence. Among these classification techniques, classification tree (CT) is the tree-based method which is effective in capturing the local character.

However, not all methods are effective because of the complicated characters of mass spectral data. First, the dimension of a typical piece of the data is very high. In the development of classifiers, it is evident that the generation of suitable spectral features is a crucial step (Werther *et al.* 1994). Therefore, the variables considered consist not only the original peak heights, but also a set of additional appropriate spectral features. In order not to miss all important information in the classification procedure,

it is common, just to stay on the safe side, to consider all kinds of spectral features in the development of classifiers. This makes the number of variables in certain such studies up to several hundreds (Werther *et al.* 2002). As the result the common phenomenon "curse of dimensionality" (Bellman 1961) in data mining also occurs for the mass spectral data. Secondly, it is known that complicated and widely unknown relationship between mass data and chemical structure do exist, various interactions may also present in the data. These types of interactions are even more difficult to model. For these reasons, many of the often used traditional classification methods are inefficient.

In view of these characters, a classification algorithm designed to develop the classifiers of mass spectral data should have two features: first, it can effectively select the variables which are important for classification; second, it takes various interactions into account during the modeling process. Although KNN, LDA and PCA are very useful classification methods in general, their applications to mass spectral data leave something to be desired. However, in many case studies, it has been shown that the classification tree is a powerful classification technique satisfying the above two demands. In particular, the approach proposed by Breiman *et al.* (1984) has been used to generate classifiers in analysis of mass spectral data. Moreover, its comprehensibility makes it more charm than neural networks, which usually provides result difficult to explain with subject matter knowledge.

It is known that the classification tree is weak at capturing classifiers of linear functions of the variables. In a typical mass spectral classification exercise, combinations of original peak heights are very likely to play the important role. For example, one of the numerical transformations successfully used for mass spectra classification is the summation of intensities at masses differing by a multiple of 14, which in most cases corresponds to a  $CH_2$  group (Crawford and Morrison 1968). The transformation called Modulo-14 summation feature is simply a linear combination of the variables. Unfortunately the classification tree can not detect this feature, because a classification tree is typically based on a "divide and conquer" approach and the most useful variable is selected to split into a few (mostly 2) regions at every step. A natural extension is to add new variables, e.g., using certain transformations. An important class of such transformations

consists the linear combinations of the original ones. However there are also technical considerations when we add these linear combinations as the candidates of predictors. For example, we need to address such issues as how to find useful combinations and how to add new variables into the tree model. In this paper, we propose an approach which combines the classification tree with a suitable non-linear regression technique called the sliced inverse regression (SIR). This new method recursively adds some new variables produced by SIR into a set of predictors during the process of tree induction. SIR, Li (1991), is an effective method in nonlinear regression which uses the principal components from high dimensional data. SIR has been applied to many fields successfully, but it is seldom used in chemometrics. Experiments in the paper show that our new approach can effectively improve the prediction accuracy of classification tree in mass spectral data.

The paper is organized as the follows. In Section 2 we briefly introduce the decision tree and SIR and propose our approach. Mass spectrum and mass spectral data are described in Section 3. Two spectral data sets are studied in Section 4 to illustrate our procedure. The last section gives conclusion that our approach can improvement performance of the original classification tree.

## 2. Methodology

#### 2.1 Classification tree

Classification tree has been popularized in the statistical community since the book of Breiman *et al.* (1984) was published. The method separates the sample by recursively splitting the data space till the stopping criteria are all satisfied (Friedman 1991). Suppose a data set consists of pinputs  $x_1, \dots, x_p$  and one response  $\mathbf{y}$ , for each of N observations, that is,  $(x_{(i)}, y_{(i)})$  for  $i = 1, \dots, N$ , with  $x_{(i)} = (x_{i1}, \dots, x_{ip})$ . In the binary partitions process, the algorithm of classification tree firstly creates a node and finds a splitting rule to the given data set. The splitting rule including a split variable  $x_j$  and split value " $\lambda$ " assigns observations to either left or right branch of the node. The observations with  $\{x_j < \lambda\}$  are assigned to the left branch and those with  $\{x_j > \lambda\}$  to the right respectively. Then

the data space is separated into two sub-regions. Secondly, repeat the same step in the each subspace till all the stopping criteria are satisfied. The extensive details of the algorithm can be seen in reference (Breiman *et al.* 1984).

There are many criteria based on different measures of node impurity, such as misclassification error, Gini index and deviance, to determine the choice of splitting rules in classification tree (Hastie *et al.* 2001). The criterion used in this paper is minimizing deviance. Suppose output variables **y** take value 1, ..., K and a node m, representing a region  $R_m$ , consists  $N_m$ observations  $(x_{(i)}, y_{(i)})$ , impurity measure deviance  $D_{R_m}$  is defined as

$$D_{R_m} = -\sum_{k=1}^{K} p_k \log p_k.$$
(1)

where  $p_k$  is the proportion of class k observations in this node m, i.e.

$$p_k = \frac{1}{N_m} \sum_{x_{(i)} \in R_m} I(y_{(i)} = k),$$
(2)

where  $I(\cdot)$  is the indicator function. Then at each node, representing R, the classification tree performs a greedy algorithm to seek the splitting variable  $x_i$  and split value  $\lambda$  by solving

$$(x_j, \lambda) = \min_{x_j, \lambda} \left\{ \frac{N_1}{N} \mathcal{D}_{R_1(x_j, \lambda)} + \frac{N_2}{N} \mathcal{D}_{R_2(x_j, \lambda)} \right\},\tag{3}$$

where N is the number of the observations contained in the region R, i.e. N = |R|, and  $R_1(x_j, \lambda)$ ,  $R_2(x_j, \lambda)$  are the two sub-regions obtained by using splt pair  $(x_j, \lambda)$ :

$$R_1(x_j, \lambda) = \{ \mathbf{x} | x_j \le \lambda, \ \mathbf{x} \in R \}, N_1 = |R_1(x_j, \lambda)|$$
$$R_2(x_j, \lambda) = \{ \mathbf{x} | x_j > \lambda, \ \mathbf{x} \in R \}, N_2 = |R_2(x_j, \lambda)|.$$

The decision tree is conceptually simple yet powerful. However, it has difficulty in capturing linear structure among the variables. If there exist

some linear combinations of the predictors in separating classes from the start, the classification tree will lead a weak classifier because the effect of an error caused by a single variable in the top split can be propagated down to all of the splits below it. So adding some linear combinations of the variables should improve the predictive power of the tree.

#### 2.2 Sliced inverse regression

In this subsection, we discuss the basic idea of sliced inverse regression (SIR) and present its computational algorithm, as introduced by Li (1991). SIR is an effective method in non-linear regression since it combines the good parts of principal component analysis, inverse regression and the information including the dependent and independent variables.

Suppose **X** is a  $n \times p$  matrix with *n* observations and *p* variables and **y** is a  $n \times 1$  univariate output variable. Express **X** and **y** in terms of their rows, columns and elements by

$$\mathbf{X} = \begin{pmatrix} x_{(1)}' \\ \vdots \\ x_{(n)}' \end{pmatrix} = \begin{pmatrix} x_{11} \cdots x_{1p} \\ \vdots \\ x_{n1} \cdots x_{np} \end{pmatrix} = (x_1, \cdots, x_p), \ \mathbf{y} = \begin{pmatrix} y_{(1)} \\ \vdots \\ y_{(n)} \end{pmatrix}$$

Li (1991) introduced the following model

$$\mathbf{y} = g(\mathbf{X}\beta_1, \cdots, \mathbf{X}\beta_K, \epsilon),$$

where g is an unknown function, and  $\beta_1, \dots, \beta_K$  are K unknown projection directions and the random error  $\epsilon$  is independent of **X**, but its probability distribution is unknown. Obviously, **y** is a function of some linear combinations of  $x_1, \dots, x_p$ . The K directions are used to generate the first K principal components, called effective dimension reduction (e.d.r.) direction which is our primary interest.

Based on the inverse regression, SIR inverses the role of  $\mathbf{y}$  and  $\mathbf{X}$  and treats the  $\mathbf{y}$  as if it were the independent variables and treats  $\mathbf{X}$  as if it were the dependent variable. It has been proved that if  $\mathbf{X}$  has been standardized to  $\mathbf{Z}$ , the standardized inverse regression curve  $E(\mathbf{Z}|\mathbf{y} = y)$  is contained in

the linear space spanned by the standardized e.d.r direction  $\beta_1, \dots, \beta_K$ . For details of the theory, reader are referred to Li (1991). The covariance matrix  $\Sigma_{\eta} = \text{Cov}(E(\mathbf{Z}|\mathbf{y}))$  is degenerate in any direction orthogonal to the  $\beta_k$ 's. Therefore, the normalized eigenvectors,  $\beta_k$  ( $k = 1, \dots, K$ ), associated with the first largest K eigenvalues of  $\Sigma_{\eta}$  are the standardized e.d.r directions. In the approach,  $\Sigma_{\eta}$  are estimated by the slice method. The details are shown in the following algorithm of sliced inverse regression:

- 1. Standardize **X** into  $\tilde{\mathbf{X}}$ , where  $\tilde{x}_{(i)} = \hat{\boldsymbol{\Sigma}}_{xx}^{-1/2}(x_{(i)} \bar{x})$   $(i = 1, \dots, n)$ , where  $\bar{x}$  and  $\hat{\boldsymbol{\Sigma}}_{xx}$  are the sample mean and sample covariance matrix of **X** respectively.  $\hat{\boldsymbol{\Sigma}}_{xx}^{-1/2}$  is the inverse of the positive definite square root of  $\boldsymbol{\Sigma}_{xx}$ .
- 2. Sort the data  $\mathbf{y} = (y_{(1)}, \cdots, y_{(n)})'$  from the smallest to the largest.
- 3. Divide data set into H slices according to the sequence of  $\mathbf{y}$ :  $n_h$  is the sample size in the slice  $I_h, h = 1, 2, \dots, H$ .
- 4. Within each slice, compute the sample means i.e.,  $\hat{x}_h = n_h^{-1} \sum_{y_{(i)} \in I_h} \tilde{x}_{(i)}$ .
- 5. Compute the sample covariance matrix for the slice means of  $\hat{x}_h$ , weighted by the slice sizes

$$\hat{\Sigma}_{\eta} = n^{-1} \sum_{h=1}^{H} n_h(\hat{x}_h)(\hat{x}_h)'.$$

- 6. Find the eigenvalues of  $\hat{\Sigma}_{\eta}$ ,  $\lambda_1 \geq \cdots \geq \lambda_p$  and associated eigenvectors  $\hat{\beta}_1, \cdots, \hat{\beta}_p$ . The *i*th eigenvector  $\hat{\beta}_i$  is called the *i*th SIR direction.
- 7. Project  $\hat{\mathbf{X}}$  along the first K SIR directions to form principal components.

Similar to principle component analysis, SIR chooses the first K(K < p) directions, where K is often determined by the accumulative contribute rate of eigenvalues  $\sum_{i=1}^{K} \lambda_i / \sum_{i=1}^{p} \lambda_i$ , In practice, K is commonly chosen so that the

cumulative contribute rate up to  $80\% \sim 90\%$  or more. Note that there are some differences between principal component analysis (PCA) and SIR. SIR constructs the new explanatory variables considering the information of both **X** and **y** whereas PCA's new variables are determined by only the values of **X**. The directions found by SIR are the ones that make **y** change quickly.

In classification, H, the number of slices, equals to the number of groups and each group forms a slice. Then we can find linear combinations of original variables by the above algorithm. Obviously, the new variables can be directly used in construction of a decision tree. Based on the above discussion we proposed the following method combining classification tree and SIR.

## 2.3 Approach combining classification tree and SIR

In our approach the vector of predictors are expended by the principal components found by SIR. However, only adding new variables into the decision space prior to the tree induction, the same defects of subtree discussed earlier still exists in subspace after splitting the decision space. So we add new attributes recursively, that is, after the original region is split into two sub-regions, we apply SIR to current data set in each sub-region to find the new principal components and add them into the vector of predictors to join the next selection of the splitting rule.

Given a data set same with that in subsection 2.1, algorithm of the Classification Tree combined with SIR (CTS) includes six steps, as following:

- 1. Assume current node m, representing the region  $R_m$ , contain  $N_m$  samples. Apply SIR to the  $N_m$  samples and find the principal components to form the new variables.
- 2. Add the new variables to the set of predictors. (Let  $\tilde{p}$  be the number of predictors at this step)
- 3. Generate candidate splitting value set  $\{\lambda_{ij}\}$  for each predictor  $x_j, j = 1, \dots, \tilde{p}$ . Here,  $\lambda_{ij} = (\tilde{x}_{ij} + \tilde{x}_{i+1,j})/2, i = 1, \dots, N_m 1$  and  $\tilde{x}_{1j}, \dots \tilde{x}_{N_m j}$  is a sequence of ordered value obtained by sorting samples according to the value of the predictor  $x_j$ .

- 4. Select the splitting rule  $(x_j, \lambda)$  using equation(3) from candidate splitting pair set  $\{(x_j, \lambda_{ij})\}, i = 1, \dots, N_m 1, j = 1, \dots, \tilde{p}$ .
- 5. Generate two child branches and nodes to represent  $R_{m1}$  and  $R_{m2}$ which are obtained by splitting the region  $R_m$ ,  $R_{m1} = \{x_{(i)} | x_{ij} < \lambda \& x_{(i)} \in R_m\}$ ,  $R_{m2} = \{x_{(i)} | x_{ij} > \lambda \& x_{(i)} \in R_m\}$ .
- 6. Calculate the deviance of the two sub-regions and memorize the number of samples in the two sub-regions. If  $D_{R_{m1}} \leq \alpha$  or  $D_{R_{m2}} \leq \alpha$ , the corresponding branch is terminated as a leaf. If  $N_{m1} \leq \beta$  or  $N_{m2} \leq \beta$ , the corresponding branch is also terminated as a leaf. Then the leaf is assigned as the class k with the maximum proportion  $P_k$  (defined in equation (2)). Otherwise, repeated the Step1 - Step5 for each child node until the deviance of each child node is less than  $\alpha$  or the number of samples contained in each child node is less than  $\beta$ .

Usually  $\alpha = 0.05 \sim 0.1$ ,  $\beta = 5$ . Smaller  $\alpha$  or  $\beta$  will generate a bigger tree with higher accuracy in training but easily lead to over-fitting.

In this approach, SIR directions at every step should be reserved to make sure that the samples need to be predicted can be projected along the same directions to produce new variables during the process of prediction. Then the samples can be inferred according to the training tree. We have succeeded to apply this approach to classification of mass spectra as shown in subsection 4.

## 3. Mass Spectral Data

#### 3.1 Mass spectrum

Mass spectrum is one of the most important spectra in chemometrics. It is the graphical representation of mass-to-charge ratio (m/z, mostly z=1) of separated ions versus abundance (peak height). For example, Figure 2 shows a mass spectrum of  $C_2H_4O$ , called acetaldehyde. A mass spectrum is produced by instrumental technique, Mass spectrometry, which is commonly use to character and identify chemical organic. The distribution of peaks in a mass spectrum is very characteristic for a compound, although not unique. Main information obtained from a mass spectrum is molecular mass,

and hints about substance class and parts (substructures) of the molecular structure.



Figure 1. Mass spectrum of  $C_2H_4O$ 

In our work, mass spectra and chemical structures are taken from the mass spectral library same with (Liang and Gan 2001). This library was established by transferring NIST62 mass spectrum library, which is built in the GCMS-QP5000 of shimadzu. The aim of spectra evaluation is either finding the relationship between mass spectra and chemical structures or identifying structure properties of an unknown compound from its spectrum. So in classification of mass spectral data, commonly, the height of peak at every m/z or spectral features (defined in the next subsection) are always considered as input variables,  $x_1, \dots, x_p$ , and the chemical structure properties, for example, the presence or absence of a certain chemical substructure, as response variables.

#### 3.2 Spectral feature

In the following experiments, the vector of predictors includes not only the original peak heights of mass spectra but also a set of features obtained by transforming the original peaks. These spectral features are included because the following considerations:

1. As shown in earlier work, appropriate spectral features are simpler in molecular structures than the original peak heights of mass spectra (Lohninger and Varmuza 1987 and Varmuza 1998).

- 2. Although tree structure can detect interactions of variables and SIR can find the useful linear relationships, some simpler relationships are not presented yet.
- 3. Decision tree has powerful ability on variable selection. If a spectral feature is irrelevant, it cannot influence the model too much. On the contrary, if a useful feature is added in the process of tree induction, the accuracy will be improved and the size of tree will be reduced.

Let  $I_m$  be the intensity of a peak at mass-to-charge ratio m/z. In the following, mass-to-charge ratio m/z is simplified as mass m. They are listed below:

A. Intensities at a single mass normalized to local ion current Features of this group emphasize isolated peaks even if possessing only low intensities (Erni and Clerc 1972):

$$x_j = 100I_m / \sum I_k, \qquad k = m - \Delta m, \cdots, m + \Delta m.$$

### B. Logarithmic intensity ratios

The logarithmic intensity ratio (Werther et al. 1994) is defined by

$$x_i = 100(L_m + \ln 100)/(2 * \ln 100).$$

 $L_m = \ln(I_k/I_{k+\Delta m}), \quad I_k = \max(I_m, 1), \quad I_{k+\Delta m} = \max(I_{m+\Delta m}, 1).$ 

#### C. Modulo-14 summation

One of the first numerical transformations successfully used for mass spectra is the summation of intensities at masses differing by multiple of 14, which in most cases corresponds to a  $CH_2$  group (Crawford and Morrison 1968). They are obtained by

$$x_j = 100s_j/s_{max},$$
  
$$s_{max} = \max(s_1, \cdots, s_{14}) \quad s_j = \sum_k I_{l+14k} \quad l = 1 \cdots 14, \quad k = 0, 1, 2, \cdots$$

#### D. Autocorrelation

This feature can characterize mass differences between peaks as well as periodicities in a spectrum (Wold and Christie 1984):

$$x_j = 100 \sum_m I_m I_{m+\Delta m} / s_0, \quad s_0 = \sum_m I_m I_m$$

### 4. Experiment

In this section we apply the approach proposed in subsection 2.3 to mass spectral data. Two case studies are discussed.

#### 4.1 Data precessing

In practice, at every step of finding SIR directions, the variables for which the range of all samples is less than 1 are removed in order to avoid the arithmetic problem caused by calculating the inverse of matrix. Mass spectral data are inaccurate data. They are influenced by noise. Although we do not know the exact value of noise, it is sensible to think the noise is not less than 1. So if the range of the variable is less than 1, it can be regard as useless for classification. Even if the variable contributes to the classification, it can be detected by decision tree because we do not discard it in process of tree induction.

#### 4.2 Example 1

We use a simple sample to illustrate the approach proposed in this paper and to compare results with other classification methods. Alcohol and aether are isometric compounds. From library NIST62, we select all 201 compounds that belong to the two groups and molecular formulas range from  $C_5H_{12}O$  to  $C_9H_{20}O$ . The number of alcohol is 148 and that of aether is 53. From these 201 compounds, we select 141 of them at random as training sample and the remaining ones as testing sample. We assign heights of peaks at masses from 1 to 144 be the original variables because the molecular weight of  $C_9H_{20}O$  is 144. Denote the alcohol by "0" and the aether by "1". We introduce the process of the new method as follows.



Fig 2: Result obtained by approach combining DT and SIR Note: "." denotes alcohol, "x" denotes aether, "\_\_\_\_" denotes splitting rule.

First, as mentioned in section 4.1, 79 variables are obtained in the training sample by removing the variables with ranges less than 1. These variables are used to find SIR direction. In this example, we only select the first SIR direction  $\beta$  to produce the new variable because the first eigenvalue's contribute rate is greater than 90%. Let  $\mathbf{X}\beta$ , the first  $\beta$  selected, be the 145-th variable, here, to fix ideas, the design matrix  $\mathbf{X}$  has been standardized. The splitting rules based on all the 145 variables uses  $x_{145}$ at the first node, and the value 2.905 is chosen to be the split value. The whole space is divided into two subspaces according to this splitting rule. At " $x_{145} > 2.9050$ ", the algorithm has reached the stopping criterion and in this subspace, since the proportion of class "0" is great than that of class "1", i.e.  $P_0 > P_1$  (defined in equation (2)), the terminal node is set to be

"0". For the case " $x_{145} < 2.9050$ ", the algorithm goes one step further to find SIR direction for the current data set. It turns out that a new variable,  $x_{146}$ , is added into decision the space, and the splitting pair ( $x_{146}$ , 0.3566) is found. Here, the branch " $x_{146} < 0.3566$ " reaches the stopping boundary and is terminated as leaf "1". Finally, for the case " $x_{145} < 2.9050$  &  $x_{146} > 0.3566$ ", the same process is done, and all branches reach stopping boundary. The full graph (tree) is shown in Figure 2(a). The directions found by SIR at every step are shown in Appendix 1.

In prediction, first we use the same transformations on test samples with the SIR directions to generate additional variables to make the predictors. Then the first splitting rule is used to divide all the 60 testing sample. The result is shown in Figure 2(b). 38 of them fall into the subspace " $x_{145} >$ 2.9050" are predicted as "0". Here, one testing sample predicted incorrectly. The remaining 22 samples are separated by the splitting pair ( $x_{146}$ , 0.3566) as shown in Figure 2(c). There are 11 fall into the branch " $x_{146} < 0.3566$ " and therefore are predicted as "1". Here all 11 cases are predicted correctly. Finally, the third splitting rule is applied to the remain 11 samples. From Figure 2(d), we can see the third split rule does not work in this situation because values of the 33-th variable of all 11 samples are less than 0.3. There is one sample misclassified.

We use leave-one-out cross validation to compare the predictive ability of our approach CTS with that of CT and PCA. The result is shown in the column of Table 1, where the result of classification tree is calculated by the program in S-plus 2000. It is observed that the predicting ability is improved by our approach.

Data	CTS(%)	CT(%)	PCA(%)
Alcohol and aether	92.54	89.05	82.59
Nitrogenous (No features)	84.86	80.00	82.43
Nitrogenous (Including features)	90.29	87.43	84.57

Table 1: The Result of Leave-one-out Cross Validation

In order to find the relationship between the substructure and mass spectra, the classification tree obtained, using all 201 training samples with CTS, is shown in Figure 3(a), where we use 4 decision nodes to classify the

two groups. The direction found by SIR at every step is shown in Appendix 2. From the first SIR direction used to form  $x_{145}$ , we observe that variables  $x_{27}, x_{39}, x_{41}, x_{44}, x_{51}, x_{53}, x_{55}, x_{67}, x_{69}$  contributed most and  $x_{19}, x_{33}, x_{47}$ take second place. Moreover,  $(x_{27}, x_{41}, x_{55}, x_{69})$ ,  $(x_{39}, x_{53}, x_{67})$  and  $(x_{19}, x_{59}, x_{51}, x_{51})$  $(x_{33}, x_{47})$  are all  $CH_2$  groups because the masses differ by 14 or multiples of 14 in each group. The values of the SIR direction corresponding with the first two groups are about 0.2 and those corresponding with  $x_{19}$ ,  $x_{33}$ ,  $x_{47}$  are about  $\pm 0.15$ . It can be inferred that  $x_{145}$  mainly reflects the combination of some  $CH_2$  groups. Also,  $x_{146}$  formed at second step also reflects the combination of some  $CH_2$  groups. In this direction  $x_{33}$ ,  $x_{47}$ ,  $x_{44}$ ,  $x_{53}$ ,  $x_{55}$ ,  $x_{67}$  are most important. In terms of the SIR direction used to get  $x_{147}$ , we can observe  $x_{59}$ ,  $x_{60}$ ,  $x_{29}$ ,  $x_{30}$ ,  $x_{33}$ ,  $x_{39}$ ,  $x_{41}$ ,  $x_{42}$  play the important role. The values of this SIR direction corresponding with  $x_{59}$ ,  $x_{60}$  are smaller than -0.2 and those with  $x_{29}$ ,  $x_{30}$ ,  $x_{33}$ ,  $x_{39}$ ,  $x_{41}$ ,  $x_{42}$  are greater than 0.2. When we consider  $(x_{29}, x_{30}, x_{33}), (x_{39}, x_{41}, x_{42}), (x_{59}, x_{60})$  as three local groups,  $x_{147}$  may reflect the importance of the combination groups formed by some adjacent peaks.



Figure 3. Decision tree Note: (a) the first sample (b) the second sample

4.3 Example 2

In this experiment, 350 samples from nitrogenous compounds and other 350 samples from no-nitrogenous compounds are selected at random. The range of their molecular weights is from 100 to 200. To illustrate the power of our approach and to supply a comparison base against other methods, two kinds of experiments are considered. In one first case, the predictors are selected as the original peak heights. In another case, the predictors include the original peak heights as well as the spectral features. The heights of original peak at masses from 1 to 200 are the first 200 variables and the next 85 predictors are feature A (defined in subsection 3.2) for masses 15-100 with  $\Delta m=3$ ; Feature B (defined in subsection 3.2) are obtained in the mass interval [15 100] with  $\Delta m = 1$  and 2, resulting 170 features; Modulo-14 summation are performed in the mass interval 15-100, resulting in 14 features; The mass spectral feature autocorrelation, defined also in subsection 3.2, are calculated for masses in 15-100 with  $\Delta m=1$ , 2 and 14-20, resulting in 9 features. In this way 478 variables are obtained. We compare the predictive ability of our approach with that of CT and PCA using leave-one-out cross validation. The result is shown in the last two columns of Table 1. The CTS obtained, using all 700 training samples, is shown in Figure 3(b). In this tree only 7 decision nodes were used compared with 31 decision nodes produced by only using CT. We do not display these SIR directions because of the limit of space, but it is available from of one of the authors. From the result, we can observe that better classification accuracy can be obtained by CTS which incorporates the appropriate features to predictors. In fact, the improvement in accuracy can be significant. So using variables known to be important from experience and other studies is necessary.

## 5. Conclusion

In classification of mass spectra, the Classification tree is a very useful tool because mass spectral data are high dimensional and full of complex interactions. However, the classification tree is very weak in representing the linear and simpler relationship among variables and global factors. Our approach, which combines the classification tree and SIR, can make up the defect of classification tree and show improvement in predicting power.

Experimental results show that this approach can improve the classification accuracy of classification tree and reduce the size of tree. They also show that introducing the appropriate features into attributes can improve the classification ability of tree structure.

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## Appendix 1

x2	x14	x15	x17	x18	x19	x26	x27	x28	x29
0070	.0286	.0673	.1167	.1418	.1670	.0981	.2256	.1240	.1258
x30	x31	x32	x33	x36	x38	x39	x40	x41	x42
.0889	.0237	.0355	1617	0211	.1065	.2358	.1671	.1983	.0831
x43	x44	x45	x46	x47	x50	x51	x52	x53	x54
.0602	.2367	0052	0002	1392	.0824	.1959	.1303	.2597	.1093
x55	x56	x57	x58	x59	x60	x61	x65	x67	x68
.2354	.0797	0385	.0974	0310	0233	1292	.0996	.2231	.0875
x69	x70	x71	x72	x73	x74	x75	x77	x79	x81
.1992	.1092	.0584	.1051	0269	.0196	0777	.0784	0043	.1307
x82	x83	x84	x85	x86	x87	x88	x89	x95	x96
.0800	.1476	.0975	.0491	.0832	.0581	0377	1338	.0506	.0458
x97	x98	x99	x100	x101	x102	x110	x111	x112	x113
.1122	.0893	.0513	.0644	.0557	0162	.0189	.0728	.1313	.0611
x115	x116	x117	x126	x128	x129	x130	x142	x144	
0570	1346	0235	.0983	.0398	0148	0640	.0277	1360	

1. SIR direction found at the first step

2. SIR direction found at second step

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x14	x15	x18	x19	x26	x27	x28	x29	x30	x31	
0223	0313	.2231	.2213	1675	.0690	0048	1688	1788	1132	
x32	x33	x38	x39	x40	x41	x42	x43	x44	x45	
.0403	1898	1376	0155	1119	0928	1461	0629	.2261	.0367	
x46	x47	x53	x54	x55	x56	x57	x58	x59	x60	
.0105	1230	.2167	0800	.1961	1422	1584	0955	.0236	.0384	
x61	x65	x67	x68	x69	x70	x71	x72	x73	x74	
1134	0283	.3362	0169	.2552	.0454	0748	0589	0955	0352	
x75	x79	x82	x83	x84	x85	x86	x87	x88	x89	
0785	0700	.1680	.1240	.0571	.1186	.0208	.0953	0342	1049	
x97	x98	x99	x101	x102	x112	x115	x116	x117	x129	
.2501	.0391	.0831	0388	0836	.2374	0368	0857	.0841	.0159	
x130	x144									
0284	1207									

# Appendix 2

1.	SIR	direction	found	at the	first	step
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x2	x13	x14	x15	x16	x17	x18	x19	x26	x27
0085	0113	.0645	.0999	.0772	.1128	.1183	.1556	.1033	.2264
x28	x29	x30	x31	x32	x33	x36	x37	x38	x39
.1368	.1188	.0998	.0124	.0434	1518	0146	.0318	.1194	.2284
x40	x41	x42	x43	x44	x45	x46	x47	x50	x51
.1248	.1932	.0936	.0923	.2126	0100	.0183	1564	.1013	.2059
x52	x53	x54	x55	x56	x57	x58	x59	x60	x61
.1291	.2553	.1127	.2312	.0889	0275	.0959	0371	0357	1303
x65	x66	x67	x68	x69	x70	x71	x72	x73	x74
.1157	.0661	.2226	.0870	.1961	.0997	.0626	.0999	0240	.0063
x75	x77	x79	x81	x82	x83	x84	x85	x86	x87
0864	.0736	.0139	.0913	.0812	.1466	.1014	.0466	.0772	.0237
x88	x89	x95	x96	x97	x98	x99	x100	x101	x102
0436	1309	.0606	.0482	.1168	.0871	.0543	.0629	.0388	0655
x110	x111	x112	x113	x114	x115	x116	x117	x126	x128
.0231	.0783	.1114	.0277	.0238	0294	0863	0233	.1017	.0337
x129	x130	x142	x144						
0015	0914	.0273	1216						

x2	x13	x14	x15	x16	x17	x18	x19	x26	x27
0788	1760	0949	1007	0058	.1058	.1518	.1411	0043	.1507
x28	x29	x30	x31	x32	x33	x36	x37	x38	x39
.0235	.0388	.0084	.0021	0711	2935	0399	0410	.0393	.1492
x40	x41	x42	x43	x44	x45	x46	x47	x50	x51
.1043	.1838	.0725	.0352	.2052	.0166	.0108	2998	.0603	.1756
x52	x53	x54	x55	x56	x57	x58	x59	x60	x65
.1109	.2531	.0900	.2376	.0812	.0066	.1009	0488	0241	.0722
x66	x67	x68	x69	x70	x71	x72	x73	x74	x75
.0679	.2273	.0998	.1899	.0972	.1033	.1091	0975	0192	0930
x77	x79	x81	x82	x83	x84	x85	x86	x87	x88
.0753	0880	.0897	.0863	.1526	.0977	.0860	.0901	.0039	0421
x95	x96	x97	x98	x99	x100	x101	x102	x110	x111
.0630	.0500	.1187	.0987	.0480	.0667	0095	1414	.0313	.0808
x112	x113	x114	x115	x116	x126	x128	x129	x130	x142
.1123	.0281	.0282	.0420	1199	.1064	.0349	.0543	.0363	.0282

# 2. SIR direction found at second step

# 3. SIR direction found at third step

x14	x15	x19	x26	x27	x28	x29	x30	x31	x32
0354	0364	.0859	1463	1354	0930	2702	2279	1033	0328
x33	x38	x39	x40	x41	x42	x43	x44	x45	x46
2377	1129	2235	1340	2873	2396	1569	0507	0891	1117
x47	x53	x54	x55	x56	x57	x58	x59	x60	x65
1371	.1383	1263	.0572	1560	2202	0474	.2375	.2596	0527
x67	x69	x70	x71	x72	x73	x74	x79	x83	x84
.1800	.0541	1105	.0840	0709	0871	0357	1005	.1525	0541
x85	x87	x88	x97	x98	x99	x101	x102	x115	x116
.1400	0607	1116	.0827	.0578	0786	0381	1317	.0738	1182
x129									
0926									

Note: Because the variables that may produce the arithmetic problem has been removed at every step, the i of  $x_i$  denotes the position at original variables.

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